

A REVIEW ON: WIND POWER PARAMETERS & WIND TURBINE GENERATORS

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I. ABSTRACT

The aim of this paper is to give a brief description about the power parameters and generator of wind energy conversion system. The power parameters based on power coefficient, power efficiency, power curve and tip speed ratio is explained. It is known that, generator is used to convert mechanical energy into electrical energy. Two types of generators are most commonly used in WECS i.e., synchronous generator and induction generator. The synchronous generators have DC excitation as well as permanent magnet excitation. The whole description is given in the rest part of the paper.

KEYWORDS: - Power parameters, synchronous generators, induction generators.

II. INTRODUCTION

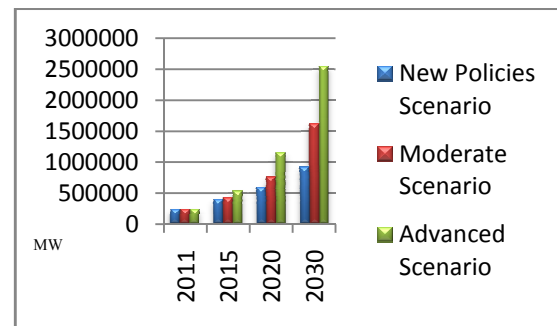
In recent years, renewable energy is the most important form of energy due to its various forms, free availability and non-polluting properties. In this renewable energy wind energy is one of the famous form of energy being used to produce electricity. In engineering technology this type of energy is known as wind conversion energy. The difference in pressure caused due to (i) Earth's rotation and (ii) Heating of earth surface, causes wind to blow from higher atmospheric pressure to lower atmospheric pressure. [1]

First larger size wind turbine was discovered by Charles Brush in 1888, whose diameter was 17 meter and it used 12 kW generator which was a DC

generator. In 1920 to 1950, 2 and 3 blades horizontal-axis WECS was developed. During this period the major change in generator take place i.e. AC generators replaced DC generators. In 1940 to 1960 rural electrification in US and Europe leads to decline in WECS use. [2], [3]

Depending on the wind energy at site the total cost of wind power ranges from 6.5 cents/kWh to 13.5 cents/kWh. By 2015 the wind energy cost will further reduce to about 5.3 cents/kWh to 6.3 cents/kWh making wind energy competitive with conventional source of power. Average life of wind turbine is about 20 years. [4]

The Global Cumulative Wind Power Capacity is shown in the graph below [5]:



III. WIND POWER PARAMETERS [6]-[9]

1. POWER COEFFICIENT: -

With the help of wind blades the kinetic energy of wind is converted into mechanical energy which is used to drive the shaft of wind generator.

The power coefficient C_p use foe converting efficiency in first stage is given us:

$$C_p = \frac{P_{me.out}}{P_w} = \frac{P_{me.out}}{(1/2)\rho A \bar{u}^3} \quad (1)$$

Where,

$P_{me.out}$ – Captured mechanical power

P_w – Available wind power

ρ – Air density

A – Blade swept area

\bar{u} – Wind speed

2. POWER CONVERSION EFFICIENCY:-

The total power conversion efficiency from wind to electricity is given by η_l

$$\eta_l = C_p \eta_{gear} \eta_{gen} \eta_{ele} \quad (2)$$

Where, η_{gear} – Gearbox efficiency

η_{gen} – Generator efficiency

η_{ele} – Electrical efficiency

The effective power becomes:

$$P_{eff} = C_p \eta_{gear} \eta_{gen} \eta_{ele} P_w = \eta_l P_w = \frac{1}{2} (\eta_l \rho A \bar{u}^3) \quad (3)$$

3. POWER CURVE: -

Power curve determines the curve between wind speed and the power output of wind turbine. The power output increases with the increase in with the increase in wind speed until it reaches the saturated point where it is define as the rated output power. At the rated speed with the increase in wind speed the output

power will not increase due to activation of power control and wind speed will reach up to cut-out speed where the wind turbine need to be shut down. The cut-in and cut-out speed is defined as the operating limit of wind turbine.

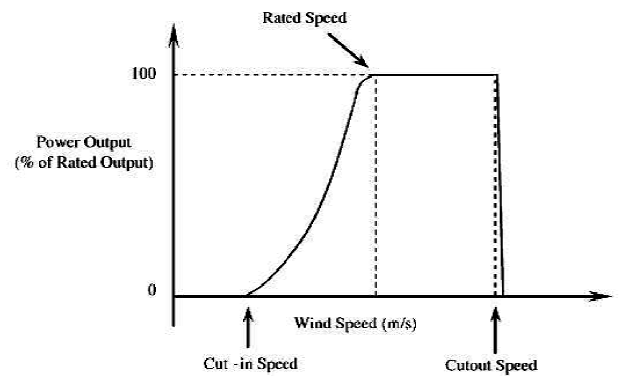


Fig: Typical Wind Turbine Power Curve

4. TIP SPEED RATIO: -

Rotor that space rotates slowly will allow the wind to pass uninterruptedly through the gaps between the blades. A rotor rotating rapidly will appear as a solid wall to the wind. For obtaining maximum or optimal speed ratio it is necessary to design wind turbine to match the angular velocity of rotor. Therefore the relationship between wind speed and rate of rotation of rotor is known as tip speed ratio or lambda.

$$\lambda = \frac{(l+r)\omega}{\bar{u}} \quad (4)$$

IV. TYPES OF WIND TURBINE GENERATORS

1. SQUIRREL CAGE INDUCTION GENERATOR (SCIG):-

SCIG is generally used due to their ruggedness, low cost and low maintenance. For frequency-insensitive load it is able to maintain near constant terminal voltage [10],[11]. Voltage equation for stator and rotor reference frame is [12]-[14]:

$$v_{ds} = R_s i_{ds} + \frac{d\lambda_{ds}}{dt} - \omega_s \lambda_{qs} \quad (5)$$

$$v_{qs} = R_s i_{qs} + \frac{d\lambda_{qs}}{dt} + \omega_s \lambda_{ds} \quad (6)$$

$$v_{dr} = 0 = R_r i_{dr} + \frac{d\lambda_{dr}}{dt} - (\omega_s - \omega_r) \lambda_{qr} \quad (7)$$

$$v_{qr} = 0 = R_r i_{qr} + \frac{d\lambda_{qr}}{dt} + (\omega_s - \omega_r) \lambda_{dr} \quad (8)$$

$$\lambda_{ds} = L_s i_{ds} + L_m i_{dr} \quad (9)$$

$$\lambda_{qs} = L_s i_{qs} + L_m i_{qr} \quad (10)$$

$$\lambda_{dr} = L_r i_{dr} + L_m i_{ds} \quad (11)$$

$$\lambda_{qr} = L_r i_{qr} + L_m i_{qs} \quad (12)$$

The electromagnetic torque is:

$$T_e = \lambda_{qs} i_{ds} - \lambda_{ds} i_{qs} \quad (13)$$

Active and reactive power can be given as:

$$P_s = v_{ds} i_{ds} - v_{qs} i_{qs} \quad (14)$$

$$Q_s = v_{ds} i_{qs} - v_{qs} i_{ds} \quad (15)$$

2. DOUBLY FED INDUCTION GENERATOR (DFIG): -

DFIG also known as wound rotor induction generator have application in WECS. When motoring operation is compared the power handling capability of

DFIG is nearly double. It is coupled to wind turbine through gearbox. The gearbox gear ratio should be so chosen so that it's synchronous speed false nearly in middle of the allowable speed of turbine. The stator is directly connected to fixed-frequency utility grid whereas rotor is connected to the grid through back-to-back PWM converter. Rotor side PWM converter is stator flux controlled which provides independent control of active and reactive power.[15]

Synchronous reference frame equations are [16]-[19]:

$$v_{ds} = \frac{d\lambda_{ds}}{dt} - \omega_g \lambda_{qs} \quad (16)$$

$$v_{qs} = \frac{d\lambda_{qs}}{dt} + \omega_g \lambda_{ds} \quad (17)$$

$$v_{dr} = R_r i_{dr} + \frac{d\lambda_{dr}}{dt} - \omega_s \lambda_{qr} \quad (18)$$

$$v_{qr} = R_r i_{qr} + \frac{d\lambda_{qr}}{dt} - \omega_s \lambda_{dr} \quad (19)$$

$$\lambda_{ds} = L_m i_{dr} \quad (20)$$

$$\lambda_{qs} = L_m i_{qr} \quad (21)$$

$$\lambda_{dr} = L_r i_{dr} \quad (22)$$

$$\lambda_{qr} = L_r i_{qr} \quad (23)$$

3. WOUND-FIELD SYNCHRONOUS GENERATOR (WFSG):-

In this type of synchronous generator DC excitation take place. Voltage equation for field winding in reference frame is given as[20]:

$$v_{ds} = R_s i_{ds} + p \lambda_{ds} - \lambda_{qs} \omega_e \quad (24)$$

$$v_{qs} = R_s i_{qs} + p \lambda_{qs} + \lambda_{ds} \omega_e \quad (25)$$

$$v_{os} = R_s i_{os} + p \lambda_{os} \quad (26)$$

$$0 = R_k i_{dk} + p \lambda_{dk} \quad (27)$$

$$0 = R_k i_{qk} + p \lambda_{qk} \quad (28)$$

$$v_f = R_f i_f + p \lambda_f \quad (29)$$

$$\lambda_{ds} = L_d i_{ds} + L_{md} (i_f + i_{dk}) \quad (30)$$

$$\lambda_{qs} = L_q i_{qs} + L_{mq} i_{qk} \quad (31)$$

$$\lambda_{os} = L_{ls} i_{os} \quad (32)$$

$$\lambda_{dk} = L_{md} (i_{ds} + i_f) + L_{dk} i_{dk} \quad (33)$$

$$\lambda_{qk} = L_{mq} i_{qs} + L_{qk} i_{qk} \quad (34)$$

$$\lambda_f = L_f i_f + L_{md} (i_{ds} + i_{dk}) \quad (35)$$

The electromagnetic torque in d^e-q^e frame is given as:

$$T_e = \frac{P}{2} (\lambda_{ds} i_{qs} - \lambda_{qs} i_{ds}) \quad (36)$$

Torque and speed are related as:

$$T_e = \frac{2J}{P} \frac{d\omega_e}{dt} + T_l \quad (37)$$

4. PERMANENT MAGNET SYNCHRONOUS GENERATOR (PMSG):-

In PMSG, the DC field winding of rotor is replaced by permanent magnet. In this the excitation field is provided by permanent magnet of coil. Neither they require DC supply for excitation circuit, nor do they have slip rings and contact brushes[21]. Advantages-

- i. Elimination of field copper loss
- ii. Higher power density
- iii. Lower rotor inertia
- iv. Robust construction of rotor

v. No gearbox

Stator voltage equation by space vector theory is [22]-[24]:

$$v_d = L_d \frac{di_d}{dt} - R_s i_d + p \omega_r L_q i_q \quad (38)$$

$$v_q = -L_q \frac{di_q}{dt} - R_s i_q + p \omega_r (-L_d i_d + \Psi_f) \quad (39)$$

Where,

R_s - Stator resistance

v_d & v_q - 2-axis machine voltage

i_d & i_q - 2-axis machine current

p - Number of poles

ω_e - Generator electrical rotational speed

Mechanical output torque is given as:

$$T_e = \frac{3}{2} P [\Psi_f i_q - (L_d - L_q) i_d i_q] \quad (40)$$

When, $L_d = L_q = L_s$ & $i_d = 0$:

$$v_d = \omega_e L_s i_q \quad (41)$$

$$v_q = -L_s \frac{di_q}{dt} - R_s i_q + \omega_e \Psi_f \quad (42)$$

And electromagnetic torque is given as:

$$T_e = \frac{3}{2} P \Psi_f i_q \quad (43)$$

V. CONCLUSION

The study on wind power parameters and generators has been done which give us the brief idea about wind energy conservation system and also the latest scenario has been given. Though this study

we came to know about the factors on which wind power depends upon and how the modelling of different generators has been done.

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